




EGR-314 Team-208 (Abner Oaxaca, Enyinnaya Onyenso, Joaquin Jimenez, Panagiotis Levendis)

1. Determine your project-specific requirements		3. Look up specifications in the PIC datasheet		
Design Considerations	Team Project-Specific Requirements from Problem Definition and Block Diagram	PIC Option 1	PIC Option 2	PIC Option 3
How many GPIO Pins? ¹	30	36 	34 	12 
Built-in Analog to Digital Converter? How many?	1	1	1	1
Built-in Hardware PWM? How many?	4	4	6	2
Built-in I2C? SPI? How many?	2/1	2/1	2/3	2/2
Built-in UART? How many?	2	2	4	1
Other Required Built-In Features? <i>(optional)</i>				
Additional considerations specific to your project specifications <i>(optional)</i>	Operation Voltage Min.(V)	1.8V	2.0V	2.2-5V
2. Find 3 microcontrollers that meet your team project-specific requirements and find information on each		4. Look up part details in the PIC datasheet		

¹ No PIC16F887, PIC16F917, PIC18F47Q10, or dsPICs allowed

Microcontroller Considerations	Instructions	PIC Option 1	PIC Option 2	PIC Option 3
Part Number ²	<i>Include the entire part number (leave off any letters at the end that specify the package type)</i>	PIC18F46K42	PIC24FJ128GB204	PIC16F18325
Link (URL) to product page	<i>Do not paste links directly into the table. Instead, link them like this.</i>	Product page	Product page	Product page
Links (URL) to Data Sheets		DataSheet	DataSheet	DataSheet
Links (URL) to Application Notes	<i>Often provided by manufacturers to give you specific examples of how to use their products. Search for them in the search bar on the Microchip's website.</i>	Application Note Writing code for PIC16 and PIC18		Application Note Writing code for PIC16 and PIC18
Links (URL) to Code Examples				
Links (URL) to External Resources	<i>Search on Google and YouTube for other resources for each specific microcontroller.</i>			
Production Unit Cost	<i>Find in the Microchip online store, or Digikey</i>	\$2.54	\$5.38	\$1.60
Supply Voltage Range	<i>Find in the microcontroller datasheet</i>	2.3V-5.5	2V-3.6V	2.3V-5.5

² General Purpose Input/Output Pins - calculate based on your block diagram and include at least 20% more than you need. Avoid using In-System Programming (ISP) pins for GPIO.

		V		V
Absolute Maximum Current for entire IC	<i>Find in the microcontroller datasheet</i>	350mA	300mA	250mA
Maximum GPIO Pin Current (Source/Sink)	<i>Find in the microcontroller datasheet</i>	+/-50mA	200mA	+/-20mA
8-bit or 16-bit Architecture	<i>Find in the microcontroller datasheet</i>	8-bit	16-bit	16-bit
Available IC Packages / Footprints	<i>Find in the microcontroller datasheet. Choose a microcontroller with both surface mount and DIP/through-hole packages available. See Most Common Mistakes below for requirements to improve manufacturing reliability.</i>	Surface Mount, Through hole		Surface Mount, Through hole
Supports External Interrupts?	<i>Find in the microcontroller datasheet</i>	Yes	Yes (5)	Yes
In-System Programming Capability and Type	<i>Allows for programming the microcontroller without removing it from the PCB. Find in the microcontroller datasheet.</i>	Yes, C		Yes, C
Programming Hardware, Cost, and URL	<i>Find on the microcontroller product page</i>			
Works with MPLAB® X Integrated Development Environment (IDE)?	<i>Required. See Microchip Development Tools</i>	Yes	Yes	Yes
Works with Microchip Code Configurator ?	<i>Required. Go to the MCC website, click the “Manual Downloads” tab, scroll to the device library that goes with the PIC you chose (likely “MCC 8-bit PIC”) and read the release notes to make sure your microcontroller is in the list of supported devices.</i>	Yes	Yes	Yes

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5. Write overall pros, cons, and rankings for the chosen microcontrollers				
Overall Pros	<i>Write at least 2 for each microcontroller</i>	multiple 8-bit and 16-bit timers multiple UARTS	-16-bit capability - Many UART, SPI, I2C capability	Smaller Inexpensive
Overall Cons	<i>Write at least 2 for each microcontroller</i>	limited memory capacity 8-bit instead of 16-bits	0 DAC Outputs Only 1 PWM Time Base	Less GPIO pins Less application tools
Ranking	<i>1 = first, 2 = second, 3 = third</i>	1	2	3

6. Final Microcontroller Choice: <PIC18F46K42 choice #1 >

Rationale: <We decided to go with option #1 because of the limitations the other two microcontrollers faced while option #1 passed all the tests. It also offered multiple UARTS as well as analog-to-digital. It was somewhat limited when it came to memory capacity as well as clock speed but those factors won't affect our final product. . >